

DESIGO™ PX

# Automation stations, compact model

PXC....D

PXC12.D	PXC12-T.D	PXC12-E.D
PXC22.D	PXC22-T.D	PXC22-E.D
PXC36.D	PXC36-T.D	PXC36-E.D

- Freely programmable compact automation stations for HVAC and building services.
- Native BACnet automation stations with communication via
  - BACnet over Ethernet / IP
  - BACnet over LONTALK
  - BACnet PTP (point to point)
- BTL label (BACnet communication passed the BTL test)
- PPC processor for high performance and reliable operation
- Comprehensive management and system functions (alarm management, time scheduling, trends, remote management, access protection etc.)
- 12, 22, or 36 physical inputs / outputs per automation station
- For stand-alone applications or for use within a device or system network
- Supports the following methods of operation:
  - QAX ... room units
  - Local or network-compatible operator units
  - system or web operation via system network

	These freely programmable automation stations provide the infrastructure for the provision and processing of system-specific and application-specific functions. Apart from the freely programmable control functions these units comprise integrated convenient management functions such as:
	<ul> <li>Alarm management with alarm routing throughout the whole network. Three level alarm management (simple, basic and enhanced) with safety control transmission and automatic transmission monitoring</li> <li>Time schedulers</li> <li>Trend functions</li> <li>Remote management functions</li> <li>Access protection for the whole network with individually defined user profiles and</li> </ul>
	categories
I/O points	In addition to building and system management functions, the automation stations provide control of – PXC12D: 12 inputs / outputs, – PXC22D: 22 inputs / outputs, – PXC36D: 36 inputs / outputs.
Programming language	The automation stations are freely programmable with the D-MAP programming language (follows closely CEN Standard 1131). All function blocks available in libraries are graphically linked with the plant operating programs.
Communication	Communication is via Ethernet with the international standard BACnet protocol. Both peer-to-peer communications with other automation stations and connections to the PXM20 operator units are supported.
Operation	There are various options for operation of the PXCD automation stations:
	• <b>QAX room unit</b> connected to the PPS2 interface. A <b>maximum</b> of five room units QAX (not QAX5) can be connected. Details on the PPS2 communication are described in the DESIGO Technical principles manual (chapter "I/O blocks", section "PPS2 addressing").
	<ul> <li>Local PXM10 operator unit *), connected via PXA-C1 cable</li> </ul>
	<ul> <li>The PXM20 operator unit *) connected via PXA-C1 cable, can be used either locally or decentralized for all plant connected together in one BACnet / LONTALK network</li> </ul>
Note	*) In the case of a PXCD or PXCT.D automation station, one PXM10 and one PXM20 operator unit may be connected, but not twice the same type.
	<ul> <li>The PXM20-E operator unit can be used either locally or decentralized for all plant connected together in one BACnet / IP network</li> </ul>

(connect via a hub / switch)

# **Automation stations**

	PXC12.D 1) PXC12-T.D 2) PXC12-E.D 3)	PXC22.D 1) PXC22-T.D 2) PXC22-E.D 3)	PXC36.D 1) PXC36-T.D 2) PXC36-E.D 3)
Total number of inputs / outputs	12	22	36
Number of universal inputs (UI)	4	12	18
Number of digital inputs (DI)	2	-	4
Number of analog outputs (AO)	4	4	6
Number of relay outputs (DO)	2	6	8

1) Communications BACnet / LONTALK

2) Communications BACnet / LONTALK and BACnet / PTP (point to point) (from V2.37)

3) Communications BACnet / IP

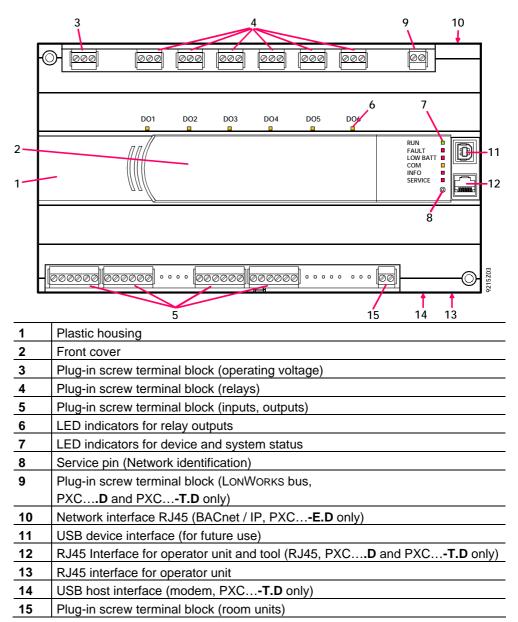
# Accessories

	Types
Connecting cable between PXM10 or PXM20operator unit and	PXA30-C1
automation station	
Adapter for firmware download	PXA30-C2
Adapter cable USB to RS232 for modems (from V2.37)	PXA30-C3

# Technology

Inputs	<ul><li>Passive sensors</li><li>Active sensors</li><li>Binary inputs</li><li>Counters</li></ul>	0 10 V
Outputs	other hand, can be prog functions. – Analogue 0 10 – Binary 0 or D	ersal outputs (AO) can control modulating actuators and, on the grammed via the program structure for binary switching ) V C24 V, max. 22 mA are designed for max. AC 250 V, 2 A.
Power Supply		des regulated power to the inputs / outputs and active sensors. mation station housing, simplifying installation and
		s with the processor to ensure smooth power up and power e equipment controlled by the I/O points, even through brownout
	Brownout protection an power fluctuations.	d power recovery circuitry protect the automation station from

The compact construction enables the automation stations to be used in highly confined spaces and makes them especially suitable for compact control panels or technical equipment with integrated control panels.



#### **Terminal blocks**

The terminal blocks are removable for easy termination of field wiring.

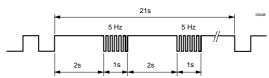
#### LED indicators

RUN FAULT LOW BATT COM INFO SERVICE
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LED	Color	Activity	Function
RUN	Green	Continuously off	No supply
		Continuously on	Supply OK
FAULT	Red	Continuously off	ОК
		Continuously on	Fault
		Quick flashes	Missing / Corrupt Firmware
LOW	Red	Continuously off	Battery ok
BATT		Continuously on	Battery low - replace
COMM	Yellow	Continuously off	No Link to Hub
		Continuously on	Link to Hub
		Flashing	Communication
INFO	Red		Freely programmable
SERVICE	Red	Continuously off	ОК
(Ethernet)		Continuously on	No Link to Hub
		Flashing	No IP Address configured
		Flashing acc. to wink	Physical identification of automation
		command pattern *)	station after receiving wink command
SERVICE	Red	Continuously off	LONWORKS node is configured
(LonWorks		Continuously on	LONWORKS chip defective or service key
bus)			was pressed again
		Flashing	LONWORKS node is not configured
		Flashing acc. to wink command pattern *)	Physical identification of automation station after receiving wink command

# The other LEDs have the follow meanings:

\*) Wink command rhythm pattern:



#### Service pin

Identification of the automation station in the IP network or LONWORKS network: see "Commissioning".

#### Disposal

The unit contains electric and electronic components and must not be disposed of with domestic waste. Lithium battery, printed circuit board and housing must be disposed of separately.

The local and actual regulations must be observed.

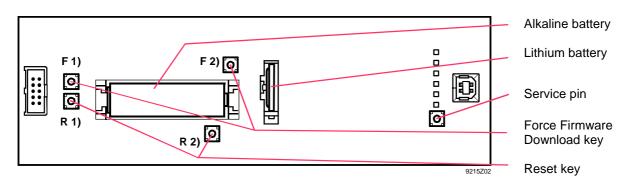
# **Mounting instructions**

The automation stations can be snap-mounted on DIN rails or directly screwed to a mounting plate or a building wall.

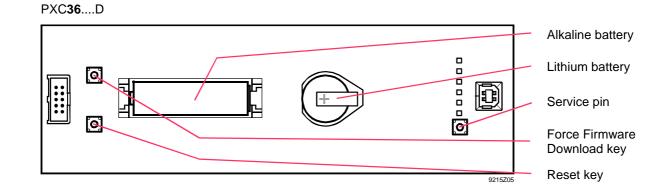
The connections for field devices and power supply are via plug-in screw terminals. The other interfaces are quick connecting jacks.

# Commissioning

	In order to prevent equipment damage and/or personal injuries always follow local safety regulations and the required safety standards.
Loading plant operating program	Download the plant operating program to the automation station with the PX Design tool in the DESIGO TOOLSET, locally via the RJ45 interface of the AS or via the Network (BACnet/IP or BACnet/LonTalk).
Setting parameters and configurations	Use the PX Design tool in the DESIGO TOOLSET for setting the control parameters and the configuration data. Data visible in the network can also be changed with a <del>PXM10 or</del> PXM20 / PXM20-E operator unit (BACnet / LonTalk or BACnet / IP). Certain data can also be changed with a PXM10 operator unit.
Wiring test	It is possible to test field devices and the wiring as soon as the power supply is connected, without first downloading the plant operating program. The test is carried out with a PXM20 / PXM20-E operator unit (BACnet / LonTalk or BACnet / IP).
Network connection	The network addresses are configured with the DESIGO TOOLSET. In order to provide a unique identification in the network (BACnet/IP or BACnet/LonTalk), press the <b>service pin</b> with a thin, long instrument or send a wink command to the relevant automation station (service LED flashes).
Force Firmware Download	If the <b>Force Firmware Download key</b> is pressed during a restart (reset) the current D- MAP program is deleted from the FLASH. The automation station waits a short while for the signal to activate the FWLoader and then starts the automation station.
Reset	Pressing the <b>reset key</b> forces a restart.



# 1) PXC12**-E.D** and PXC22**-E.D** 2) PXC12**.D**; PXC22**.D**; PXC12**-T.D**; PXC22**-T.D**



Battery life	The <b>database</b> information stored in the <b>SDRAM memory</b> is battery-backed ( <b>Alkaline</b> <b>AA Type</b> ). This eliminates the need for time-consuming program and database re-entry in the event of an extended power failure (up to 1 month). After the "Battery low" event there are several days of remaining life span under load. Alkaline batteries have a typical life span of 4 years without load.
	The <b>real time clock</b> is backed by a <b>lithium battery</b> which has a life span of 10 years.
	When one of the batteries needs to be replaced, the automation station illuminates a "battery low" status LED and automatically sends a system event. The automation station can also send an alarm message to selected terminals.
Battery change	To change the batteries, remove the front cover. As long as there is an external power supply, the battery may be removed for unlimited time.
(STOP) Caution!	To prevent hardware damage by electrostatic discharge (ESD), a wrist strap with earth cable must be used during the battery change.
Firmware upgrades	The firmware, including the operating system, is stored in non-volatile flash ROM memory. Flash ROM is easily upgradeable at the job site. This provides for ease of upgrade, as new firmware updates are made available.

# **Technical data**

General device data	•	age a-low voltage SELV or extra-low voltage PELV	AC 24 V ± 20% HD 384	
	Operating frequency		50/60 Hz	
	Power Consun	•	PXC12D max.24 VA	
	(depending	on field devices)	PXC22D max.26 VA	
	Internal fuse		PXC36D max.35 VA 5 A	
Operating data	Processor	PXC12/22D	Motorola Power PC MPC852T	
		PXC36D	Motorola Power PC MPC885	
	Memory	PXC12/22D	16MB SDRAM / 8MB FLASH (24MB total)	
		PXC36D	64MB SDRAM / 16MB FLASH (80MB total)	
	Accuracy class	8	0.5	
	Scan cycle		Max. 1 s	
	Data backup ir	n case of power failure		
		ckup of SDRAM	1 month typical	
		aline (field replaceable)	(4 years without load)	
	•	ckup of Realtime Clock Id replaceable)	10 years	

Interface, room units	Interface type Supply class PPS2 baud rate		PPS2 4 4.8 kBit	i/s
Interfaces, communication		PXC <b>D</b> , PXC <b>-T.D</b>		PXC <b>-E.D</b>
Building Level Network		LONWORKS FTT Transceiver (Screw terminals)		10 Base-T / 100 Base-TX IEEE802.3, Auto-sensing (RJ45)
Local Communication (HMI,	Tool) (RJ45)	<ul> <li>PXM10 (RS-232)</li> <li>PXM20 (BACnet/LonTalk)</li> <li>Tool</li> </ul>		-
Local Communication (HMI)	(RJ45)	<ul><li>PXM10 (RS-232)</li><li>PXM20 (BACnet/LonTalk)</li></ul>		• PXM10 (RS-232)
	-	One PXM10 operator unit and o PXM20 per automation station be connected. But not twice the same type.	may	One PXM10 on RJ45
USB host interface (Modem	)	<ul> <li>(PXC<b>-T.D)</b></li> <li>– RS232 modem via USB-RS2 adapter cable (PXA-C3)</li> </ul>	232-	
Universal inputs UI	Sensor curre Resolution Measuring en Signal inputs Contact volta Contact curre Contact trans Contact isola Counter inputs Counting free	(analog in) inputs nce e sensors NI 1000, Pt 1000, T1 ent (continuous current) rror at 25 °C (Ni 1000, PT 1000) rror at 25 °C (T1) age ent sfer resistance ation resistance quency (symmetric)	Scaling Approx. 0.2 K Max. 0. Max. 1. DC 20 . 7 mA Max. 20 Min. 50	against $\perp$ range - 50 150 °C . 2.1 mA 3 K (without cable and sensor) 0 K (without cable and sensor) 25 V 00 $\Omega$ (closed) k $\Omega$ (open)
		its faster than 1 Hz must be shie. outs for more than 10 m.	lded if the	ey are routed in the same trunking
Binary inputs DI	Contact voltage Contact current Contact transfer Contact isolation			25 V 00 Ω (closed) kΩ (open)
Analog outputs AO	Configurable by D/A Resolution ( Proportional out Output voltag Output curre Binary outputs (f Output voltag	(analog out) puts ge range nt for off-board relays)	10 bits 0 11. Max. 4 0 / DC 2	mA source, max. 1.5 mA sink
	Load		≥ 1000	Ω

⚠ Relay outputs DO… *	Relay type	single pole, change-over contact
	Contact details for AC voltage	
	Voltage range	Min. AC 10 V, max. AC 250 V
	Current, resistive load	Max. AC 5 A
	Current, inductive load	2 A
	Switching current	Min. 10 mA, max. 20 A
	Contact details for DC voltage	
	Voltage range	Min. DC 5 V, max. DC 250 V
	Switching current	Min. 100 mA at DC 5 V
	Switching load	Max. 20 W

\* The relay outputs are safely isolated from each other, from earth/cover and the remaining electronics (AC 24 V) in accordance with SELV and PELV specifications. The relay outputs can be used in mixing applications with AC 250 V and SELV / PELV circuits.

Plug-in screw terminal	Power supply and signals	Stranded of solid conductors, 0.25 2.5 mm <sup>2</sup> or 2 x 1.5 mm <sup>2</sup>
Single cable lengths and cable types	Universal inputs UI Binary inputs DI Universal outputs AO Relay outputs DO Interface, room unit Cable type Capacitance per unit length Connecting cable Ethernet and PXM20-E Cable type	Max. 100m where A = 1 mm <sup>2</sup> Max. 100 m with diameters $\ge 0.6$ mm Max. 100m where A $\ge 1.5$ mm <sup>2</sup> Depends on load and local regulations Max. 125 m where A = 1.0 mm <sup>2</sup> 2-core, twisted pair, unscreened Max. 56 nF/km Max. 100 m Standard at least CAT5 UTP (Unshielded Twisted Pair) or STP (Shielded Twisted Pair)
	Connecting cable LONWORKS bus Cable type Connecting cable PXM10	See installation manual CA110396 ConCab or CAT5 Max. 3 m
Housing protection standard Protection class	Protection standard to EN 60529 Isolation protection class	IP 20 II
Ambient conditions	Operation Climatic conditions Temperature Humidity Mechanical conditions Transport Climatic conditions Temperature Humidity Mechanical conditions	To IEC 69721-3-3 Class 3K5 0 50 °C 5 95 % rh (no condensation) Class 3M2 To IEC 69721-3-2 Class 2K3 -25 +70 °C 5 95 % rh (no condensation) Class 2M2
Standards, directives and approbations	Product safety Automatic electronic controls for household and similar use Electromagnetic compatibility Interference immunity Emitted interference	EN 60730-1 EN 61000-6-2 EN 61000-6-3
	Meets requirements for <b>CE</b> marking: Electromagnetic compatibility Low Voltage Directive UL-Approbation (UL 916) Federal Communications Commission (US) C-Tick conformity to Australian EMC Framework Radio Emission Standard	89/336/EEC 2006/95/EEC PAZX7 FCC CFR 47 Part 15 Class B Radio Communications Act 1992 AS/NZS 2064

 See "Dimensions"
 without packaging
 with packaging

 Type
 without packaging
 1.510 kg

 PXC12....D
 1.430 kg
 1.510 kg

 PXC22....D
 1.820 kg
 1.920 kg

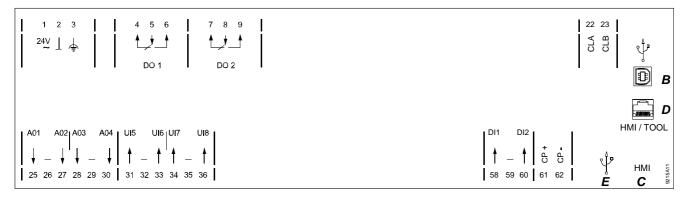
 PXC36....D
 2.520 kg
 2.620 kg

# Connection terminals

Dimensions

Weight

# PXC12.D, PXC12-T.D



1, 2	24 V ~, ⊥	Operating voltage AC 24 V
3	Ē	Functional earth
4 9	DO1, DO2	2 Digital outputs (Relays)
22, 23	CLA, CLB	LonWorks-Bus
25 30	AO1 AO4	4 Analog outputs
31 36	UI5 UI8	4 Universal inputs
58 60	DI1, DI2	2 Digital inputs
61, 62	CP+, CP-	PPS2 bus (for QAX room units)
В	-	USB Device interface (not supported)
С	НМІ	RJ45 socket for operator unit
D	HMI / Tool	RJ45 socket for operator unit and tool
E	∼ Ca⊳	USB Host interface (modem, PXCT.D only)

Caution!

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STOP

Observe the technical data for the relay outputs.

• Local installation regulations must be observed.

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$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	10     11     12     13     14     15     16     17     18       10     11     12     13     14     15     16     17     18       10     13     14     15     16     17     18       10     14     14     15     16     17     18       10     14     14     15     16     17     18       10     14     14     14     14     16     17     18       10     14     14     14     14     16     17     18       10     14     14     14     14     14     16     17     18       10     14     14     14     14     14     14     14     15       10     18     14     14     14     14     14     14       10     17     18     14     14     14     14     15       10     18     14     14     14     15     16     17       10     18     14     14     14     14     15     16     16       10     14     14     14     14     14     16     16     16	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
$ \begin{vmatrix} A01 & A02 & A03 & A04 & UI5 & UI6 & UI7 & UI8 \\ \downarrow & - & \downarrow & - & \downarrow & \uparrow & - & \uparrow & \uparrow & - & \uparrow \\ 25 & 26 & 27 & 28 & 29 & 30 & 31 & 32 & 33 & 34 & 35 & 36 \end{vmatrix} $	$\begin{bmatrix} U19 & U10 \\ 0 & 111 & U12 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} U13 & U14 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} U15 & U16 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} $	

1, 2	24 V ~, ⊥	Operating voltage AC 24 V
3	Ē	Functional earth
4 21	DO1 DO6	6 Digital outputs (Relays)
22, 23	CLA, CLB	LonWorks-Bus
25 30	AO1 AO4	4 Analog outputs
31 52	UI5 UI16	12 Universal inputs
61, 62	CP+, CP-	PPS2 bus (for QAX room units)
В	∼ Ca⊳	USB Device interface (not supported)
С	НМІ	RJ45 socket for operator unit
D	HMI / Tool	RJ45 socket for operator unit and tool
E		USB Host interface (modem, PXCT.D only)

# PXC36.D, PXC36-T.D

$\begin{vmatrix} 1 & 2 & 3 \\ 24V \\ 4V \\ D01 \end{vmatrix} = 0$	7 8 9 10 11 12 13 14 1 DO2 DO3 DO4	5     16     17     18     19     20     21     22     23     24       1     1     1     1     1     1     1     1     1       1     1     1     1     1     1     1     1       1     1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1       1     1     1     1     1     1     1	25 26 27 28 29 25 26 27 28 29 29 20 20 20 20 20 20 20 20 20 20 20 20 20	   
AO1 AO2 AO3 AO4 30 ↓ ↓ ↓ ↓ 30 31 32 33 34 35	UI9 UI10 UI11 UI12 50 1 1 4 6 50 51 52 53 54 55	UI17 UI18 UI19 UI20 DI1 DI2 32 4 4 4 7 4 74 4 62 63 64 65 66 67 74 75 76		B B HMI/TOOL
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	UI13 UI14 UI15 UI16 56 ↓ ↓ ↓ ↓ ↓ 56 57 58 59 60 61	UI21         UI22         UI23         UI24         DI3         DI4           68         68         69         70         71         72         73         77         78         79	<mark>+</mark>	HMI 5128
	<b>1 2</b> 24 V ~	Operating voltage AC 24 V		

1, 2	24 V ~, ⊥	Operating voltage AC 24 V
3	Ę	Functional earth
4 27	DO1 DO8	8 Digital outputs (Relays)
28, 29	CLA, CLB	LONWORKS bus
30 38	AO1 AO6	6 Analog outputs
39 73	UI7 UI24	18 Universal inputs
74 79	DI1 DI4	4 digital inputs
80, 81	CP+, CP-	PPS2 bus (for QAX room units)
В	∼ Ca⊳	USB Device interface (not supported)
С	НМІ	RJ45 socket for operator unit
D	HMI / Tool	RJ45 socket for operator unit and tool
E	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	USB Host interface (modem, PXCT.D only)

Caution!

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Observe the technical data for the relay outputs.

Local installation regulations must be observed. •

STOP

11/16

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	- · · · ·	
1, 2	24 V ~, ⊥	Operating voltage AC 24 V
3	Ψ <u></u>	Functional earth
4 9	DO1, DO2	2 Digital outputs (Relays)
25 30	AO1 AO4	4 Analog outputs
31 36	UI5 UI8	4 Universal inputs
58 60	DI1, DI2	2 Digital inputs
61, 62	CP+, CP-	PPS2 bus (for QAX room units)
Α		Ethernet socket
В		USB Device interface (not supported)
С	НМІ	RJ45 socket for operator unit
	•	•

# PXC22-E.D

		10 11 12 13 14 15 1 10 3 D0 4	16 17 18	19 20 21 22 23 ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓	<b>A</b> 5 5 1
					∲ 🗊 B
$ \begin{vmatrix} A01 & A02 \\ \downarrow & - & \downarrow & - & \downarrow & \uparrow & - & \uparrow \\ 25 & 26 & 27 & 28 & 29 & 30 & 31 & 32 & 33 \end{vmatrix} $	└ <b>↑ _ ↑</b>	UI10 UI11 UI12 UI13 UI14 1 1 - 1 1 - 1 2 43 44 45 46 47 48 49	UI15 UI16	+	HMI District

1, 2	24 V ~, ⊥	Operating voltage AC 24 V
3	Ψ	Functional earth
4 21	DO1 DO6	6 Digital outputs (Relays)
25 30	AO1 AO4	4 Analog outputs
31 52	UI5 UI16	12 Universal inputs
61, 62	CP+, CP-	PPS2 bus (for QAX room units)
Α		Ethernet socket
В		USB Device interface (not supported)
С	HMI	RJ45 socket for operator unit

Caution!

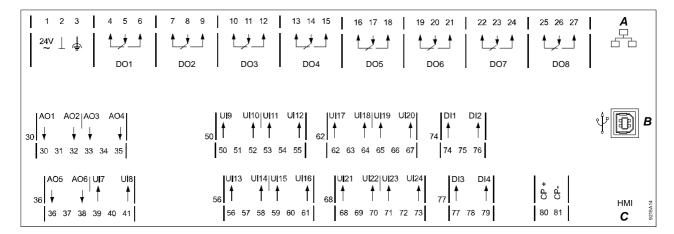
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Observe the technical data for the relay outputs.

• Local installation regulations must be observed.

12/16

STOP



1, 2	24 V ~, ⊥	Operating voltage AC 24 V
3	ĺ – –	Functional earth
4 27	DO1 DO8	8 Digital outputs (Relays)
30 38	AO1 AO6	6 Analog outputs
39 73	UI7 UI24	18 Universal inputs
74 79	DI1 DI4	4 Digitale Eingänge
80, 81	CP+, CP-	PPS2 bus (for QAX room units)
Α		Ethernet socket
В		USB Device interface (not supported)
С	НМІ	RJ45 socket for operator unit

Caution!

#### Observe the technical data for the relay outputs.

Local installation regulations must be observed.

**Pin layout** 

STOF

Tool socket "HMI" (Ethernet)

ſ		
		10
	87654321	215Z01

Automation stations for BACnet / IP

# Pin Description

- 1. Unoccupied
- 2. Unoccupied
- 3. G0. GND
- 4. G/Plus

Tool socket "HMI" (LONWORKS)

# Automation stations for **BACnet / LonTalk**



1. LONWORKS Data A (CLA)

. ..

- 2. LONWORKS Data B (CLB)
- 3. G0 / GND
- 4. G / Plus

# Pin Description5. Unoccupied

- 6. Hot-wired to Pin 8
- 7. COM1/TxD
- 8. COM1/RxD

Pin Description

- 5. Unoccupied
- 6. Hot-wired to Pin 8
- 7. COM1 / TxD
- 8. COM1 / RxD

# Connecting the field devices

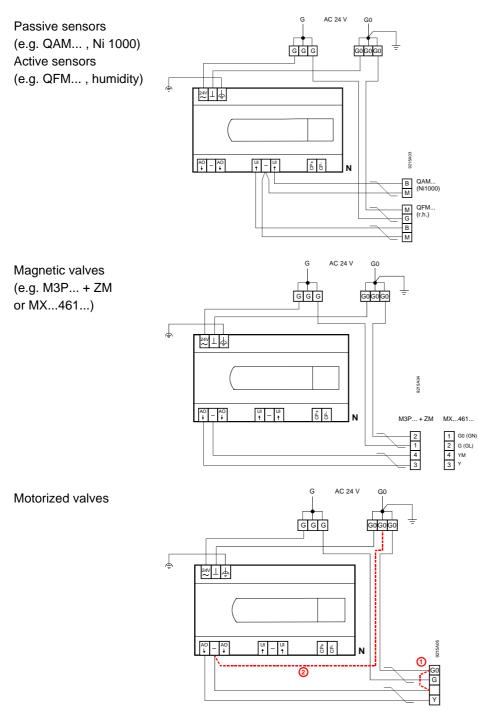
STOP	Note!	In the automation stations described in this data sheet, system neutral (G0) and measuring ground (–) are NOT CONNECTED. For active 4-wire field devices, this connection is made in the device.
		<ul> <li>For active 3-wire field devices, you have to make an additional connection:</li> <li> <ul> <li>① either on the terminals of the field device</li> </ul> </li> </ul>
		- ② or between one of the (–) terminals of the automation station and G0

(in existing plants where there are only 3 conductors installed).

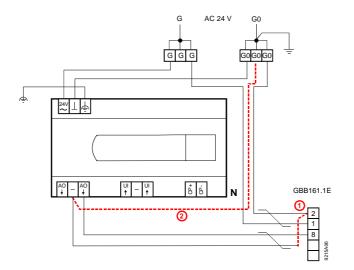
# Field device supply voltage from system transformer

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Counter inputs
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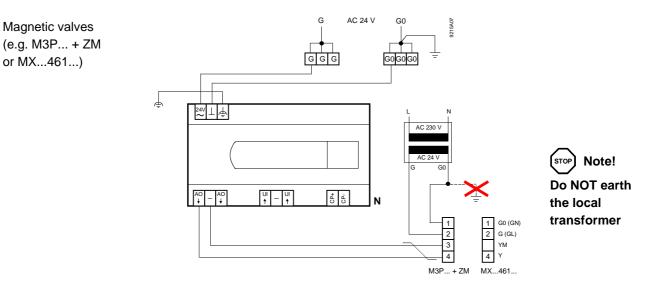
Counter inputs faster than 1 Hz must be shielded if they are routed in the same trunking as analog inputs for more than 10 m.



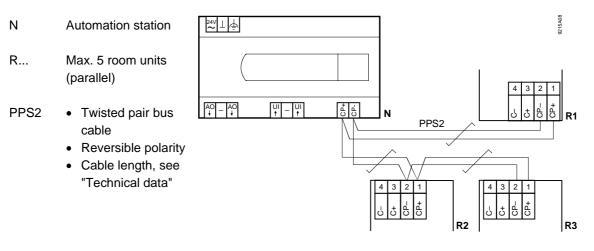
Damper actuators (e.g. GBB161.1E)



# Field device supply from separate transformer

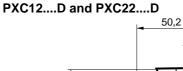


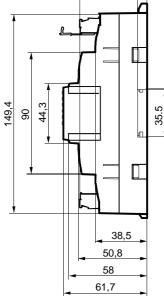
# Connecting the room units

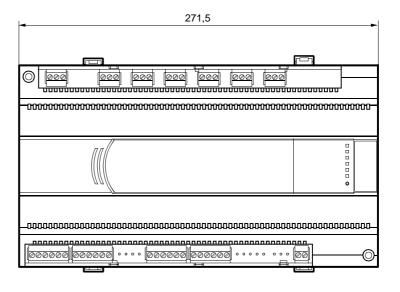


- Notes The room units are connected in parallel (max. five devices).
  - To distinguish between them, they must be addressed by use of jumpers (address plug on the printed circuit board). The factory-setting is Address 1.

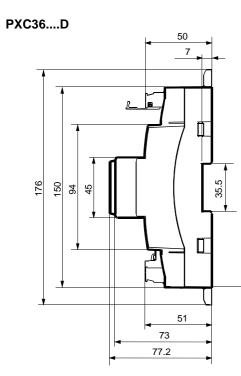
# All dimensions in mm

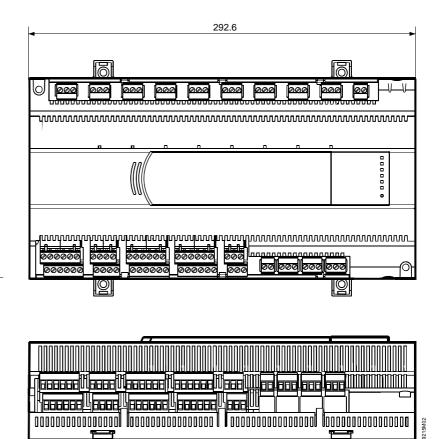






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